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Air Force Research Laboratory



Collisionless Electrostatic Shock Modeling and Simulation

Daniel W. Crews

In-Space Propulsion Branch (RQRS)

Aerospace Systems Directorate

Edwards AFB, CA

dcrews@uw.edu





Overview



- **Motivation and Background**
- **What is a Collisionless Shock Wave?**
- **Features of the Collisionless Shock**
- **The Shock Simulation Model**
- **Simulation Results and Verification**
- **Future Work**



Background



Who am I?

- Grew up in Olympia, WA, The City of Champions
- B.S. Aerospace Engineering 2016 | UW, Seattle
- Start Graduate Program at UW Autumn 2016
- Hobbies:
 - Studying classical guitar,
 - Observing the sky,
 - Appreciating existence and nature.



Investigation Motivation



What's the Point?

- **The 1D Collisionless Ion-Acoustic Shock Wave:**
 - Has a simple premise
 - Is rich in nonlinear effects difficult for theoretical prediction,
 - Wave Dispersion
 - Wave-Particle Interaction
 - Various Wave Dissipation Mechanisms
 - Shock structure is an active area of research. In particular,
 - Capacity to create ion beam of super-shock velocity.
- **Validation of Simulation Frameworks**
 - The shock is a model problem for simulation code validation.

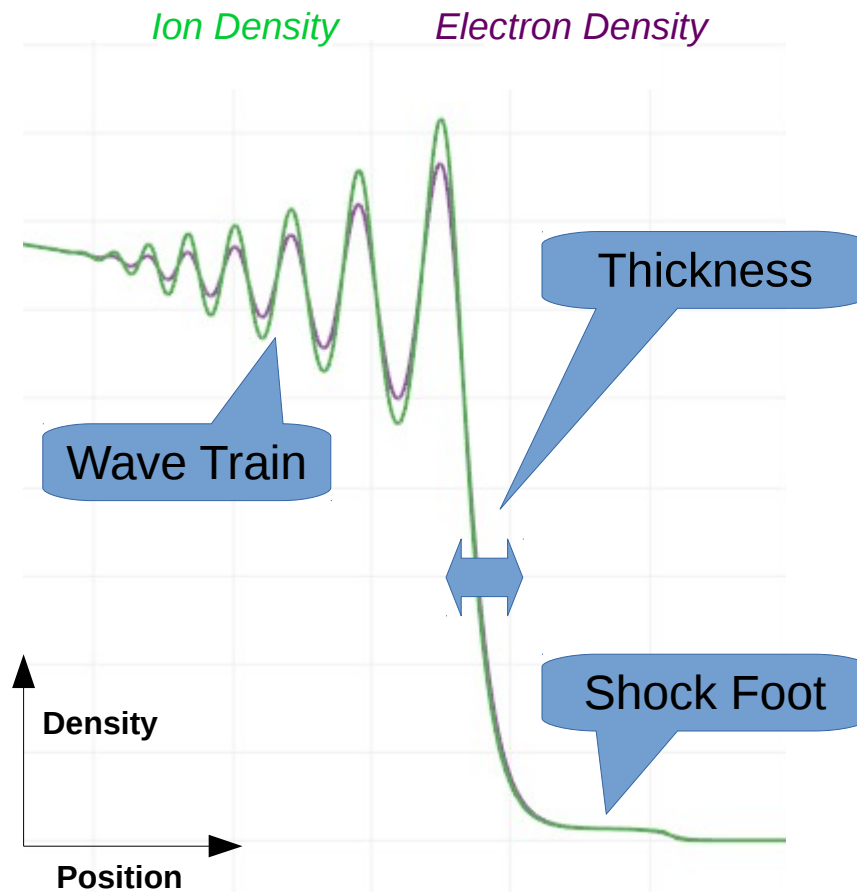


The Collisionless Shock Wave



Electrostatic Shock Features

- Propagation occurs via collective electric interactions
- Shock front is dispersed across many Debye lengths
- Wave is accompanied by an electric field perturbation
- Two classes of shock:
 - Subcritical: $M < M^* \sim 1.8$
 - Accompanied by undulating wave-train
 - Supercritical: $M > M^* \sim 1.8$
 - Increase in dissipation
 - Reflects almost all ions



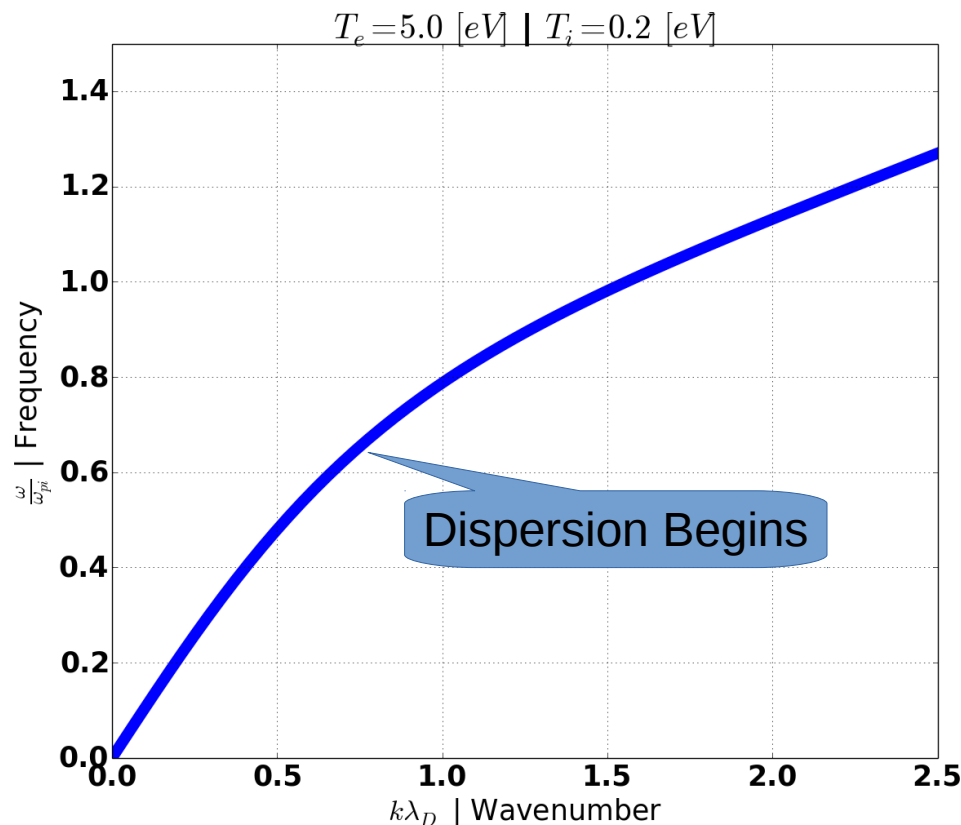


Details on Shock Structure



Shock Thickness

- Ion-acoustic dispersion relation predicts the electron contribution to acoustic speed to decay for wavelengths approaching the Debye length.
- Imagine shock formation: nonlinear steepening of an acoustic disturbance.



Wave steepening is balanced by dispersion;
short wavelength components recede from
the wavefront.

$$t \approx k_D^{-1}$$

Linearized Ion-Acoustic Dispersion Relation

$$\left(\frac{\omega}{k}\right)^2 = \frac{1}{1 + (k\lambda_D)^2} \frac{T_e}{m_i} + \gamma_i \frac{T_i}{m_i}$$



Details on Shock Structure



Wave Train Properties

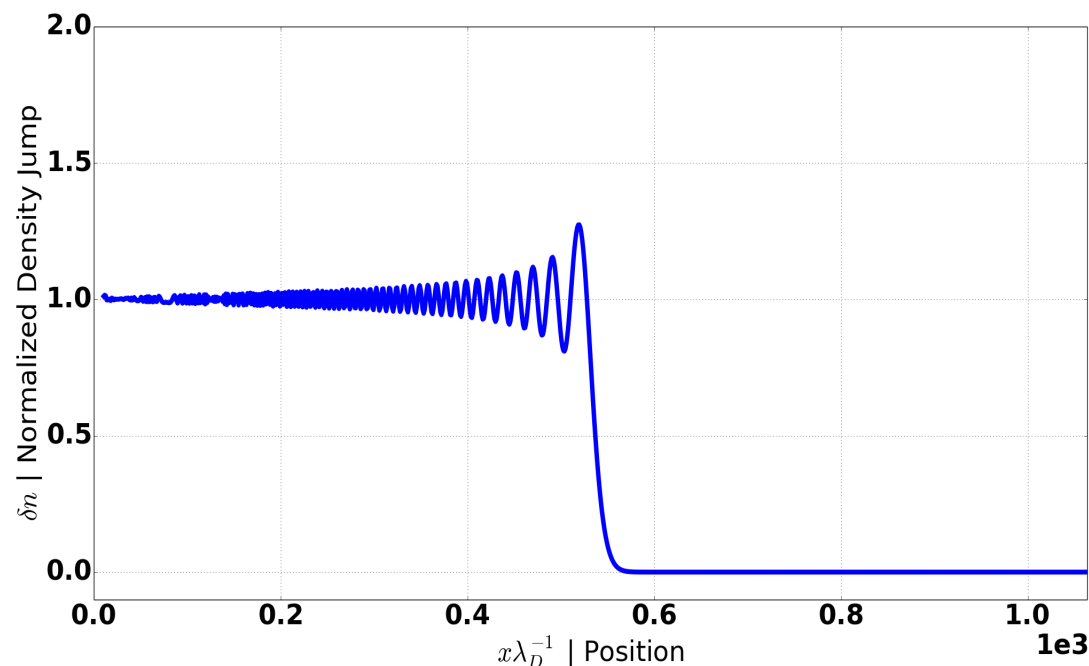
– Linearized Model of Dispersive Shock, the Integrated Airy Function:

- Linearization of the fluid equations with piston-like boundary conditions gives a solution for the shock behavior.
- Assumes cold upstream ions, therefore neglecting shock reflection.

$$n(x, t) = n_0 + \frac{\delta n}{2} \int_{\beta}^{\infty} Ai(\alpha) d\alpha$$

$$\beta = \left(\frac{2}{3}\right)^{\frac{1}{3}} \left(\frac{\lambda_D}{x}\right)^{\frac{1}{3}} \frac{(x - C_s t)}{\lambda_D}$$

$$C_s = \left(\frac{T_e}{m_i}\right)^{\frac{1}{2}}$$





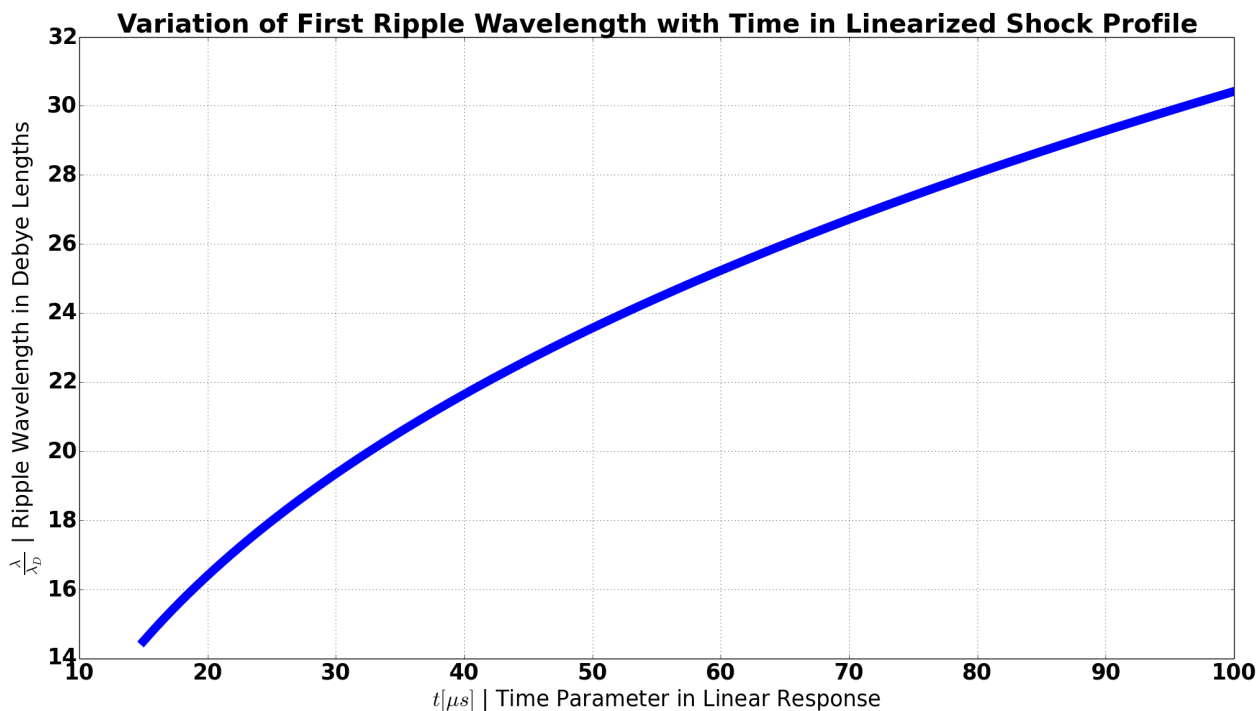
Details on Shock Structure



Wave Train Properties

– Linear Model Predicts:

- The wave train spreads out in time; peak-to-peak wavelength increases.
- No variation of non-dimensional wavelength with electron temperature.
- The wave train increases in frequency towards the back of the train.



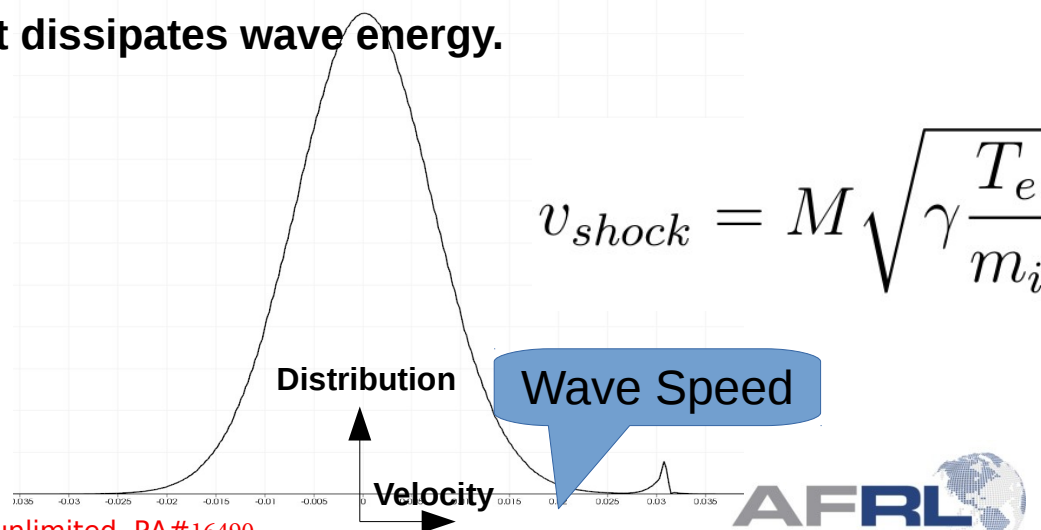


Details on Shock Physics



Sources of Collisionless Wave Dissipation

- Landau Damping:
 - A form of wave-particle resonance. Resonant particles sap wave energy.
 - Damping is proportional to slope of distribution function at wave velocity.
 - Higher electron temperature means greater shock speed, so less damping.
- Ion Reflection / The Shock Foot:
 - Higher shock strength brings a greater potential difference.
 - Ions unable to traverse difference are reflected downstream.
 - Formation of the shock foot dissipates wave energy.

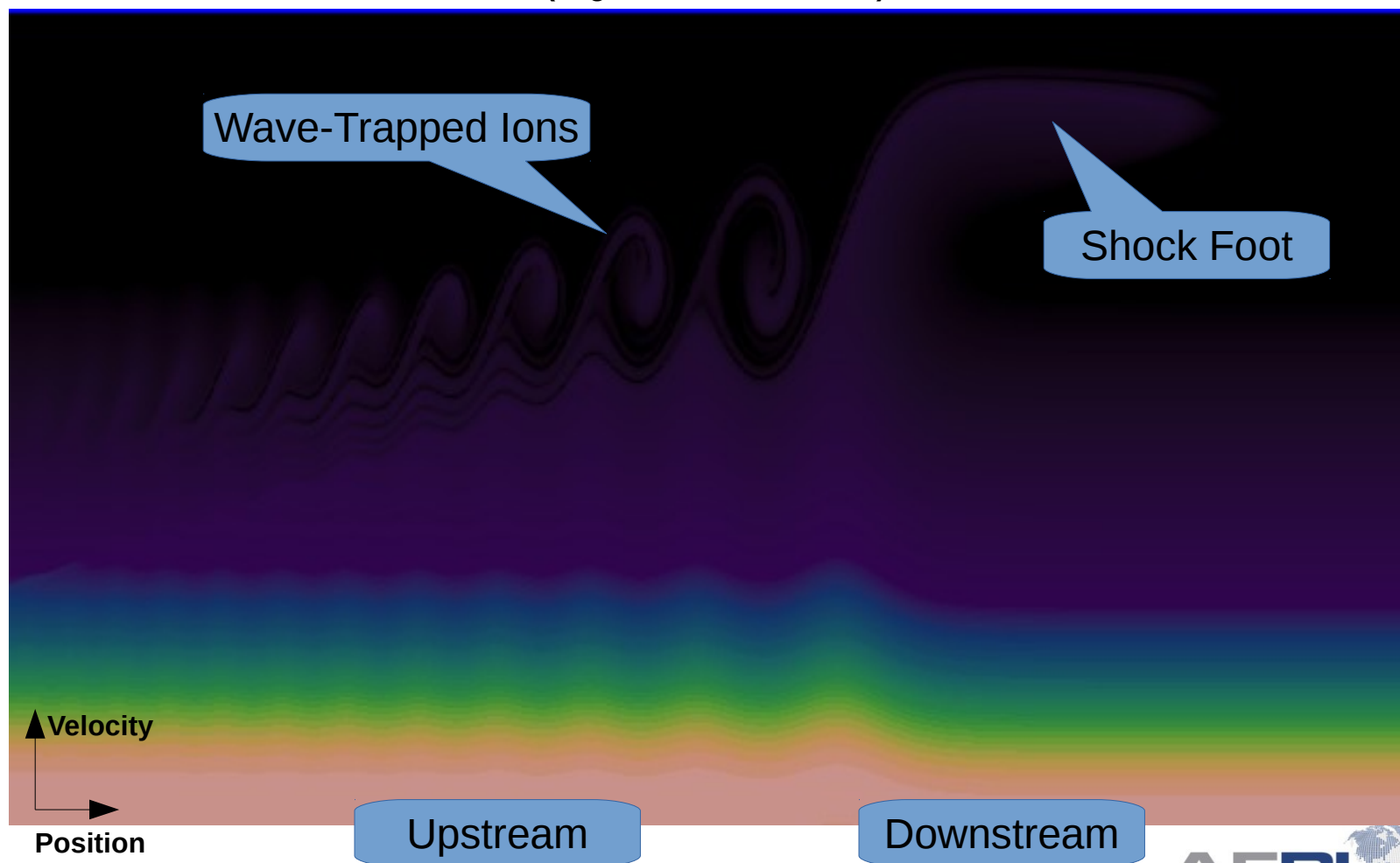




Details on Shock Physics



Phase Space Indicators of Wave Dissipation (Log View of Distribution)





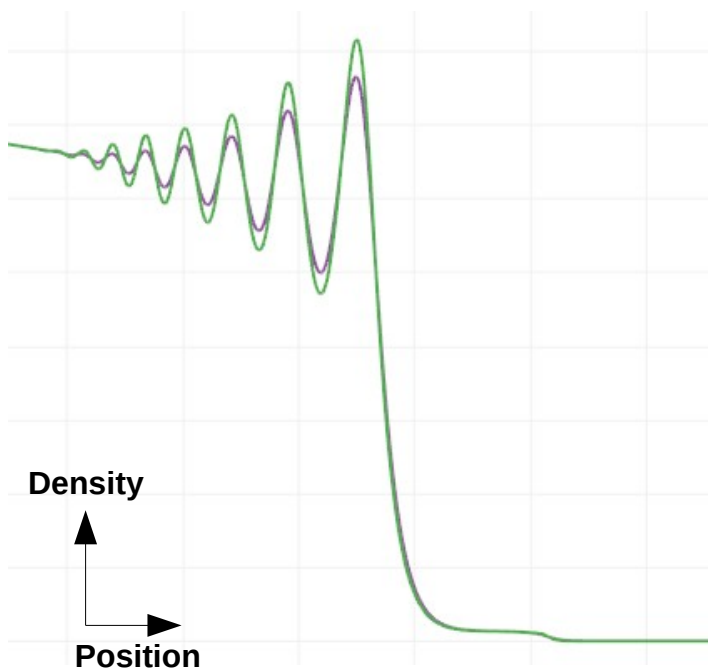
Dissipation Controls Wave Train



Under- and Over-damped Shocks

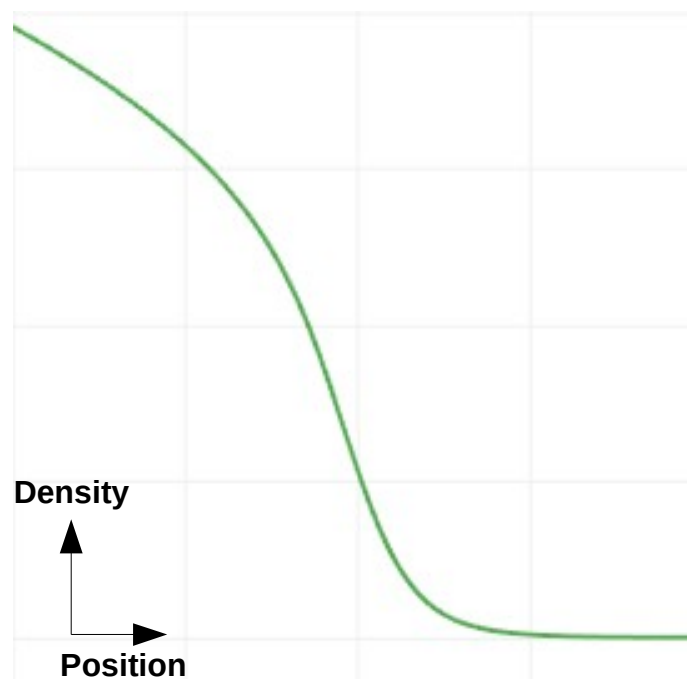
– Under-damped:

- Dissipation is weak, ripples persist.
- High $\frac{T_e}{T_i}$



– Over-damped:

- Strong dissipation damps ripples.
- Low $\frac{T_e}{T_i}$



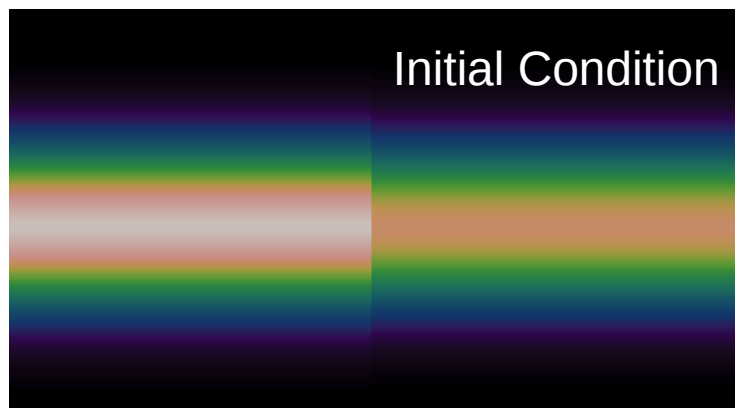


The Simulation Model

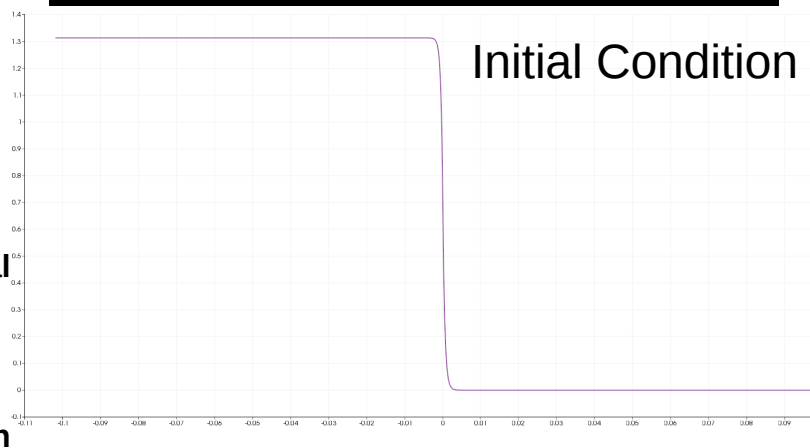
Initial Conditions: Ion-Acoustic Shock Tube

Shown: Velocity Distribution Function (VDF) $f(x, v)$
And Potential Profile $\phi(x)$

High Particle Density Low Particle Density



Velocity
Position



Potential
Position

Kinetic Model

Vlasov Equation
$$\frac{\partial f}{\partial t} + v \cdot \frac{\partial f}{\partial x} - \frac{e \nabla \phi}{m} \cdot \frac{\partial f}{\partial v} = 0$$

Poisson Equation
$$\epsilon_0 \nabla^2 \phi + \rho = 0$$

Boltzmannian Electrons
$$n_e = n_{ref} \cdot \exp \frac{\phi}{T_e}$$

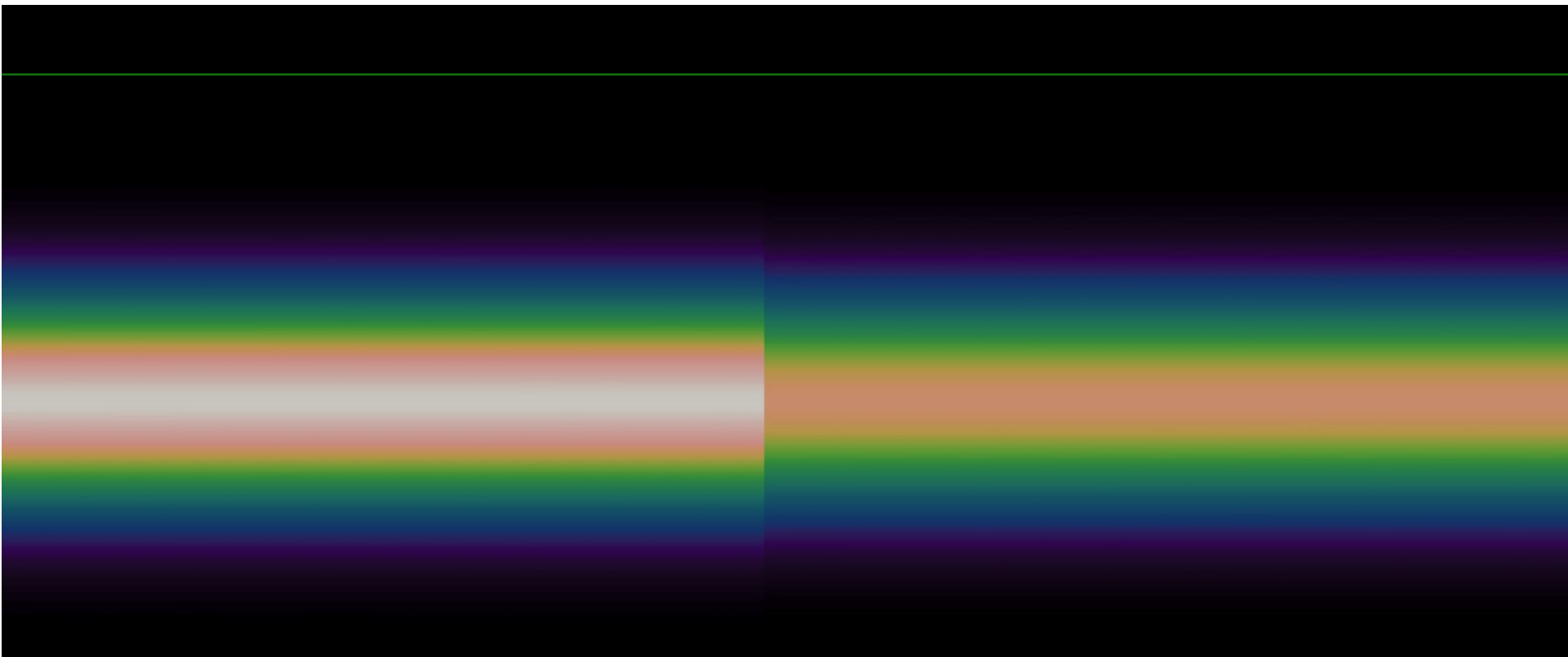
Simulation Procedure:

- Solve Poisson's equation for potential.
 - VDF for ion density
 - Electron density from $\exp \frac{\phi}{T_e}$
- Update the distribution function via Vlasov equation.
- Repeat.





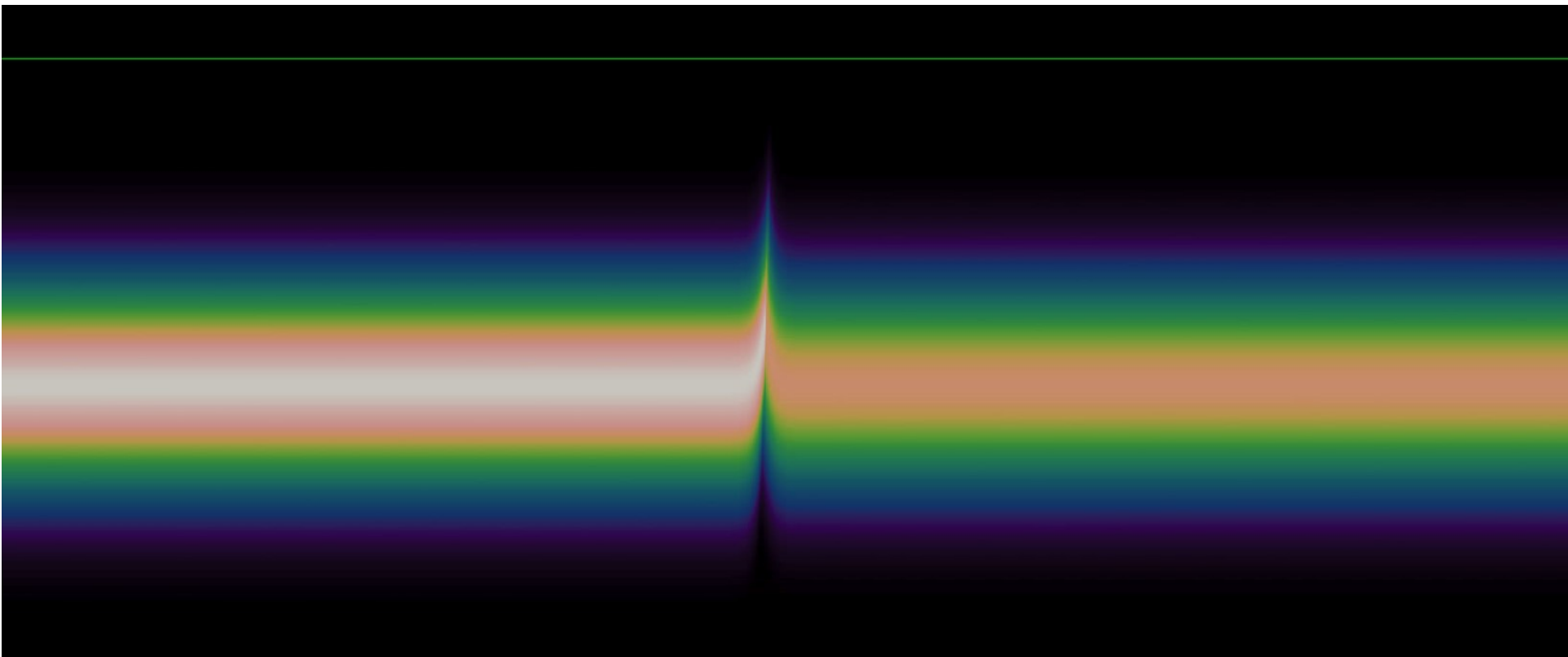
Typical Simulation Result



Lightly Damped Case
Electron Temperature: 5 eV | ($T_e/T_i = 25$)
Density Difference: 30%



Typical Simulation Result

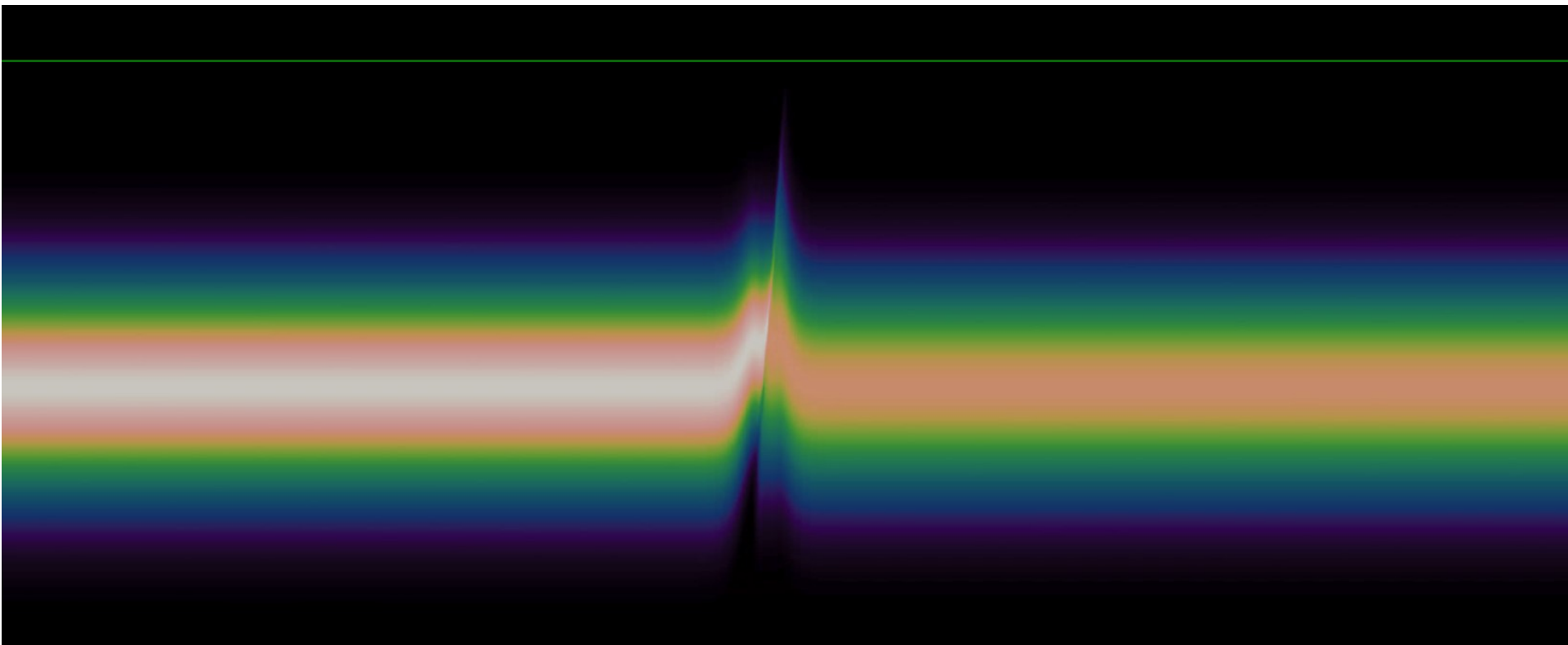


Lightly Damped Case
Electron Temperature: 5 eV | (Te/Ti = 25)
Density Difference: 30%





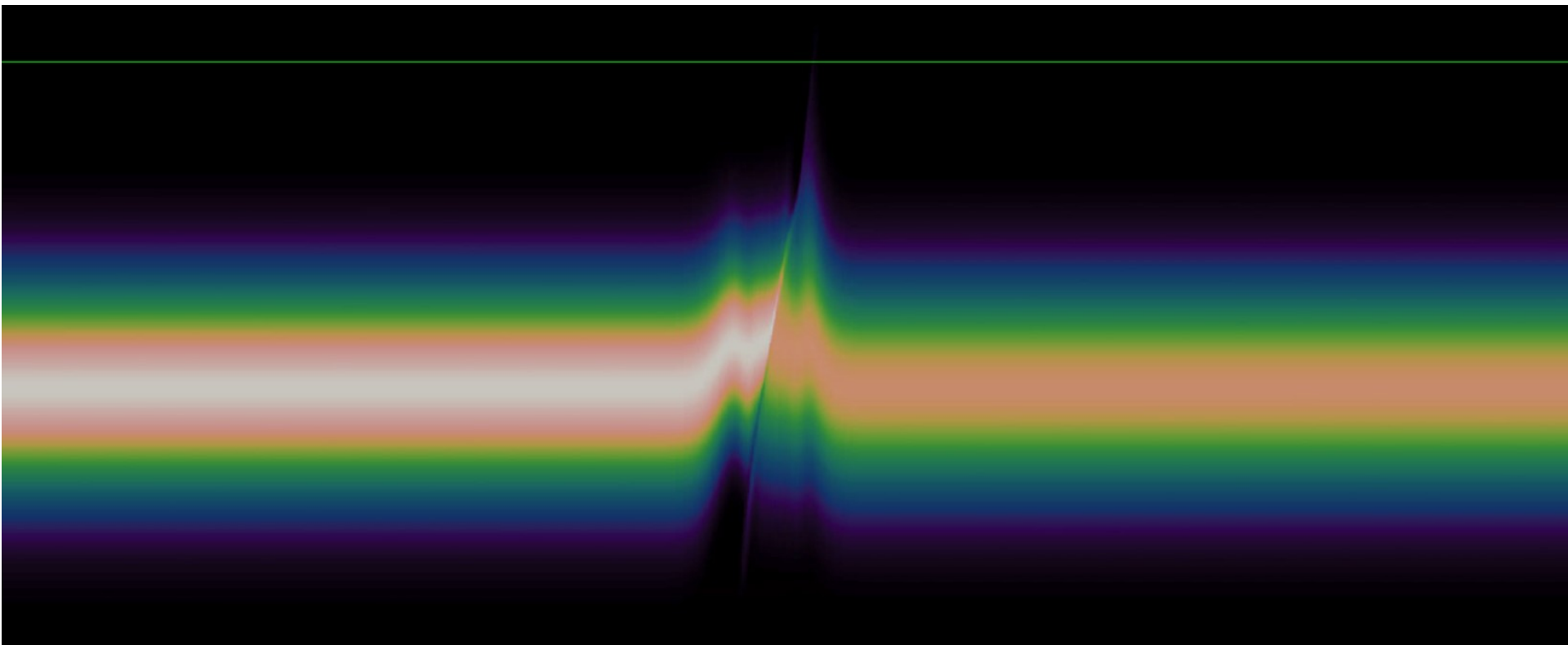
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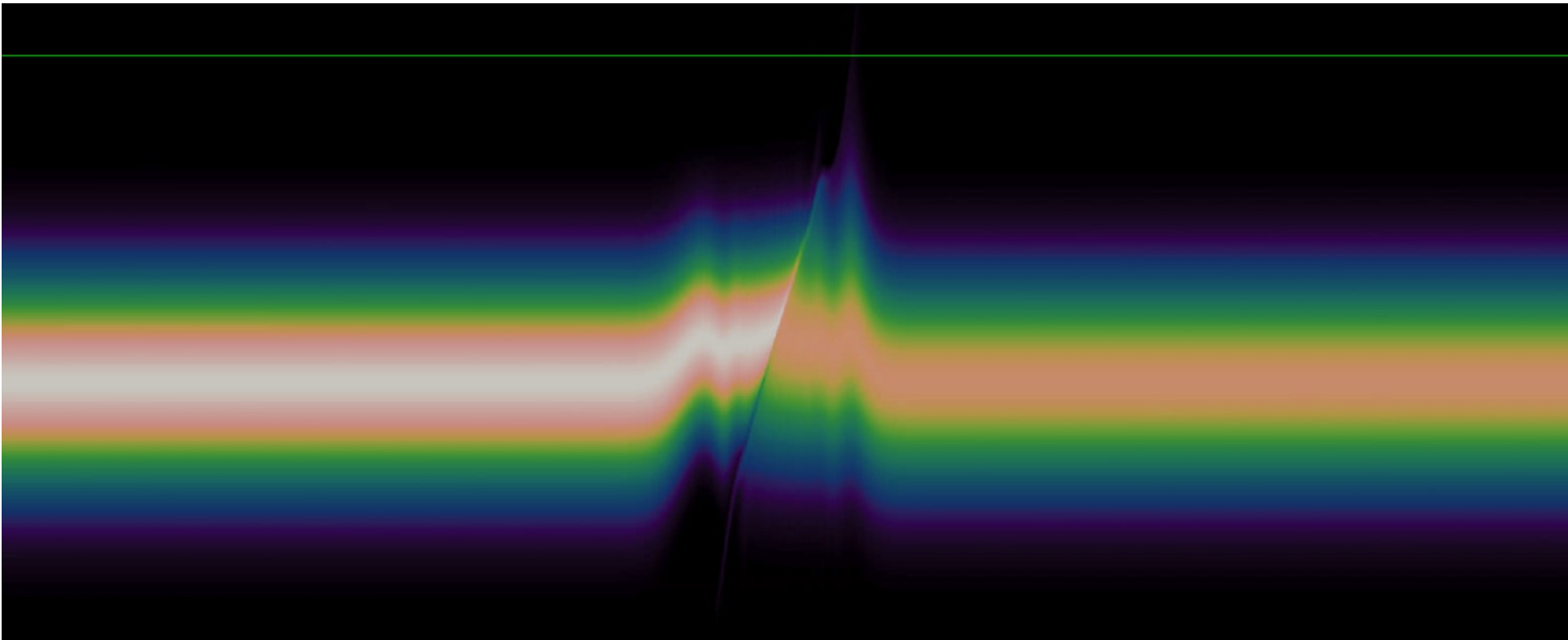
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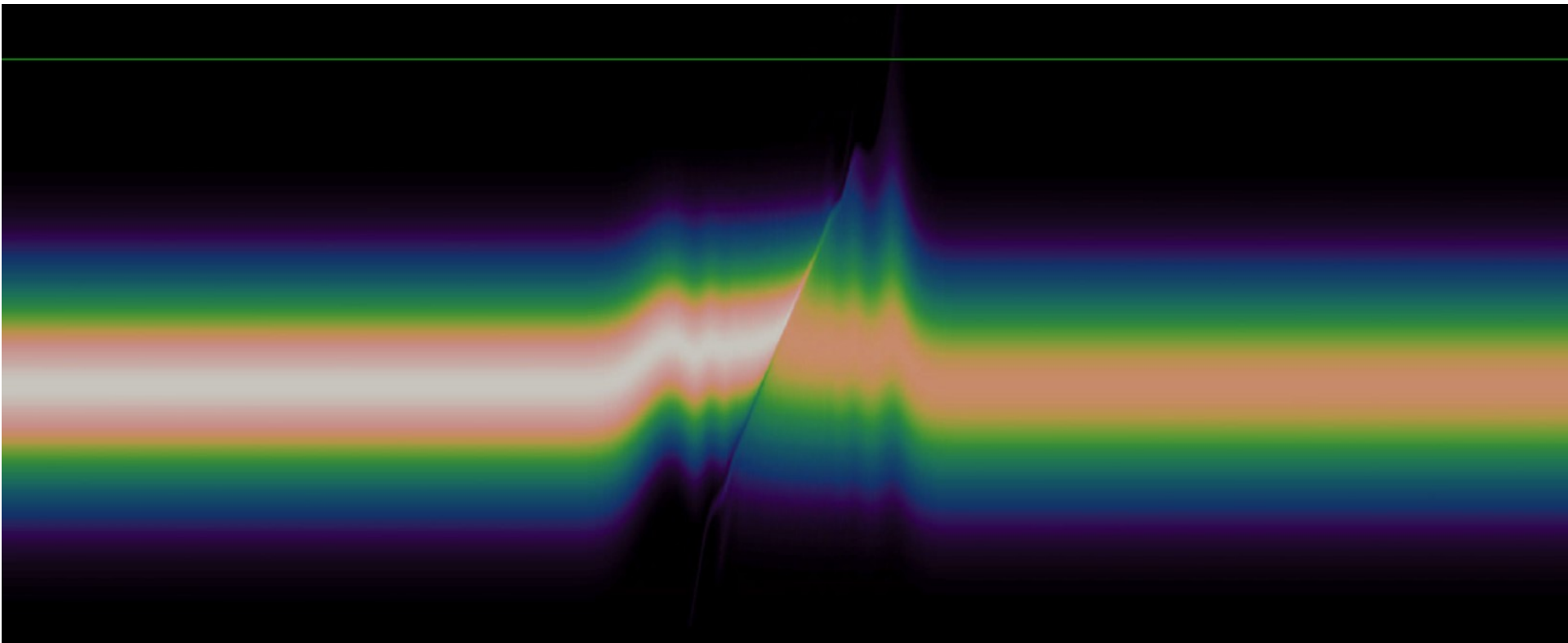
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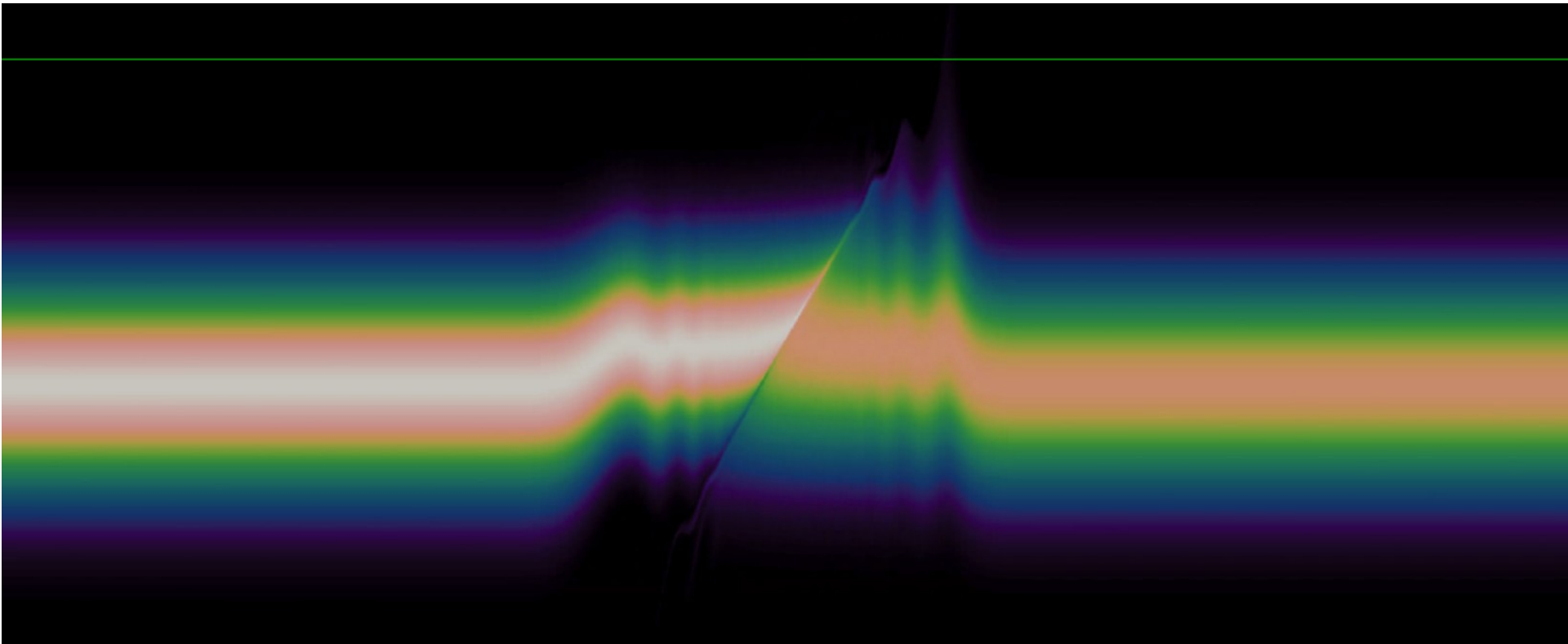
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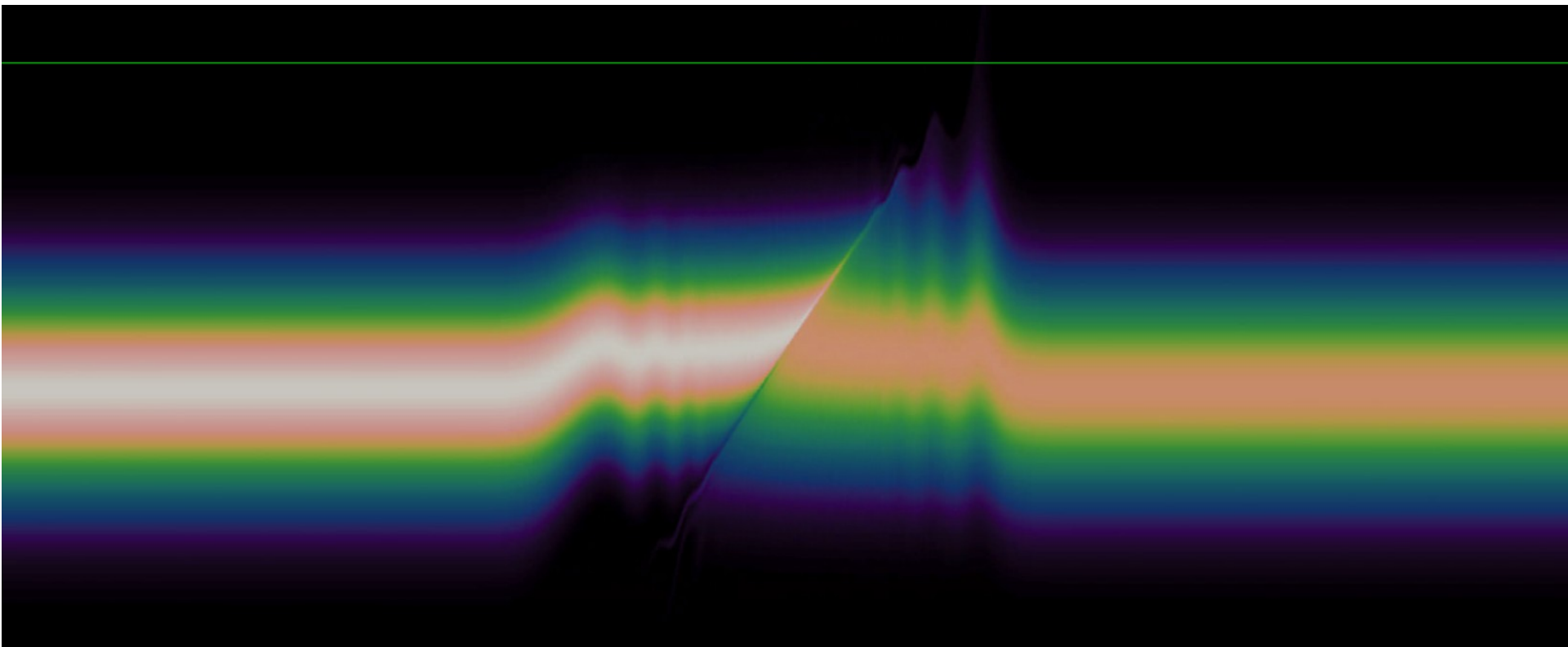
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Lightly Damped Case
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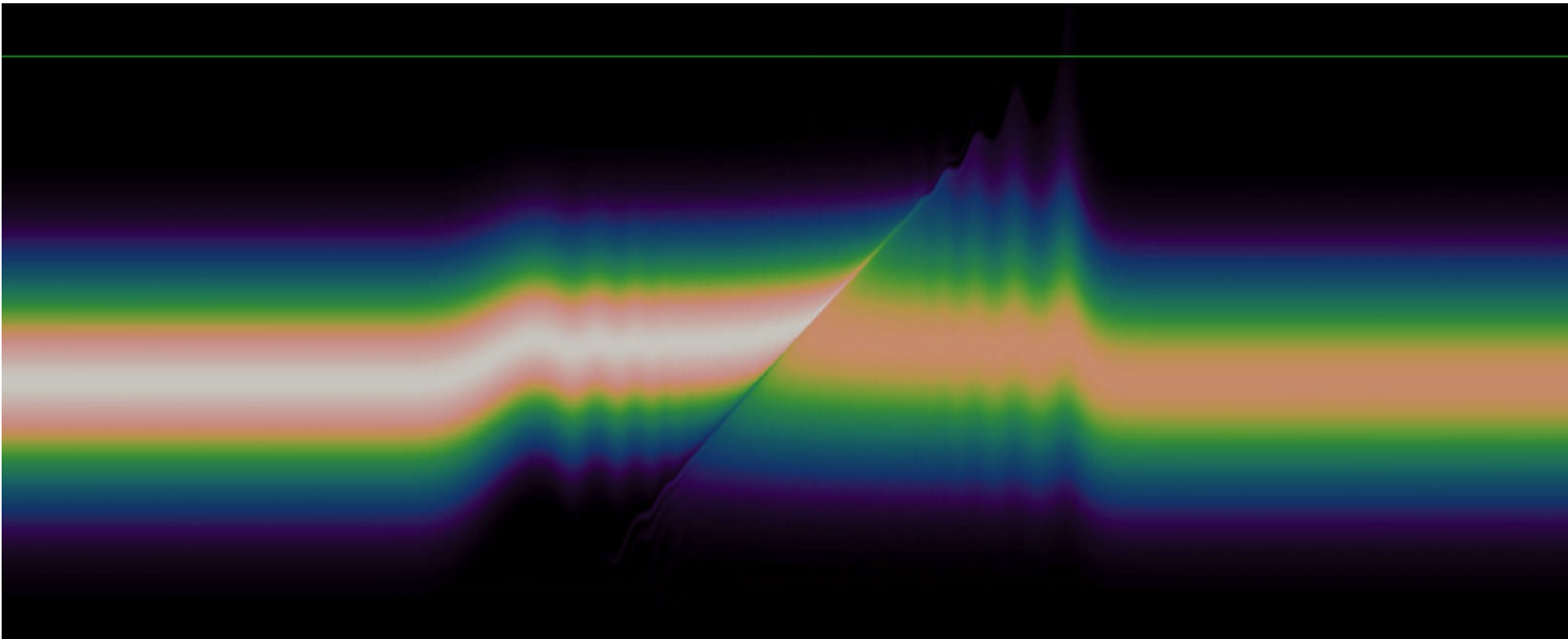
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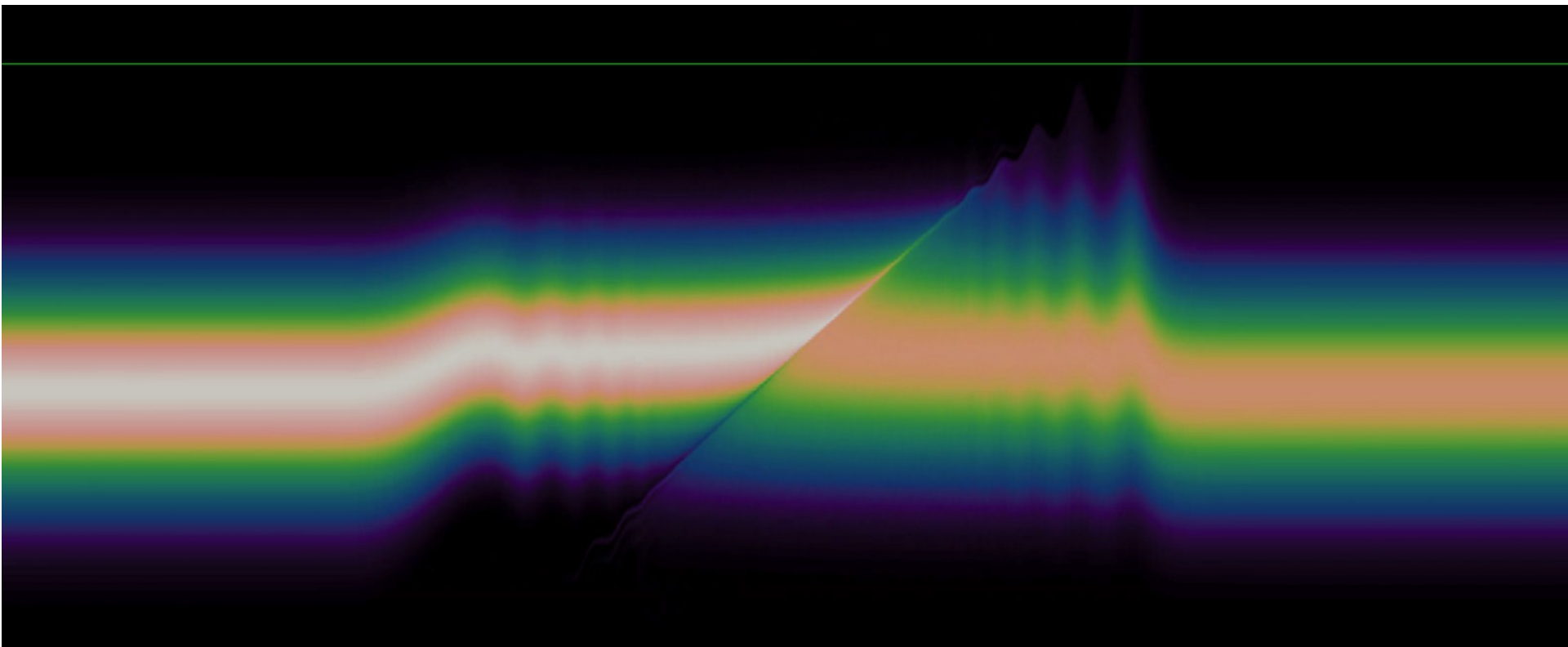
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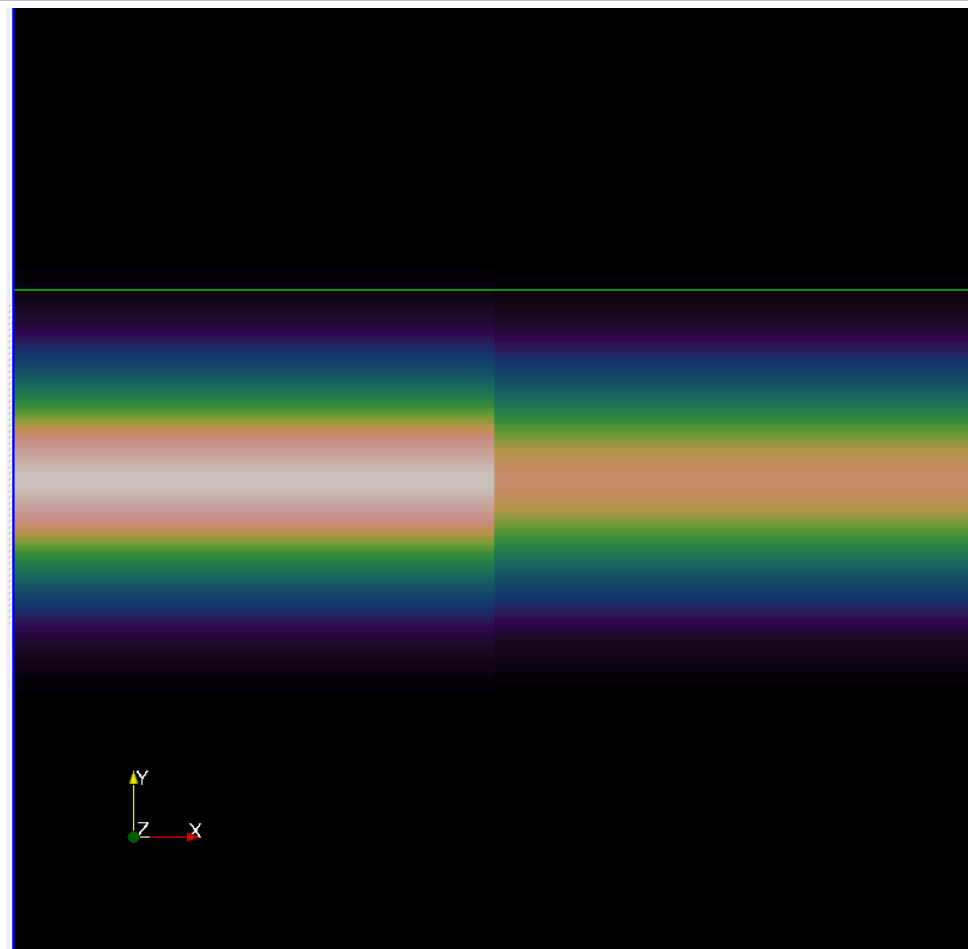
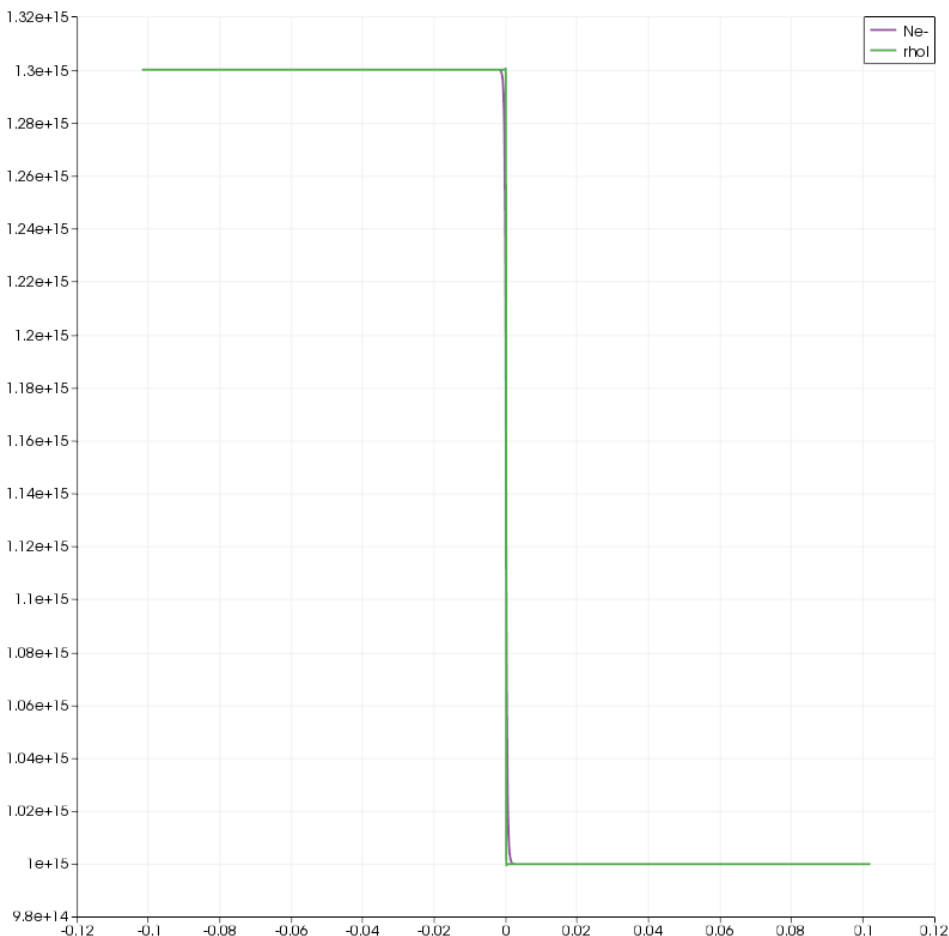
Typical Simulation Result



Lightly Damped Case
Electron Temperature: 5 eV | (Te/Ti = 25)
Density Difference: 30%



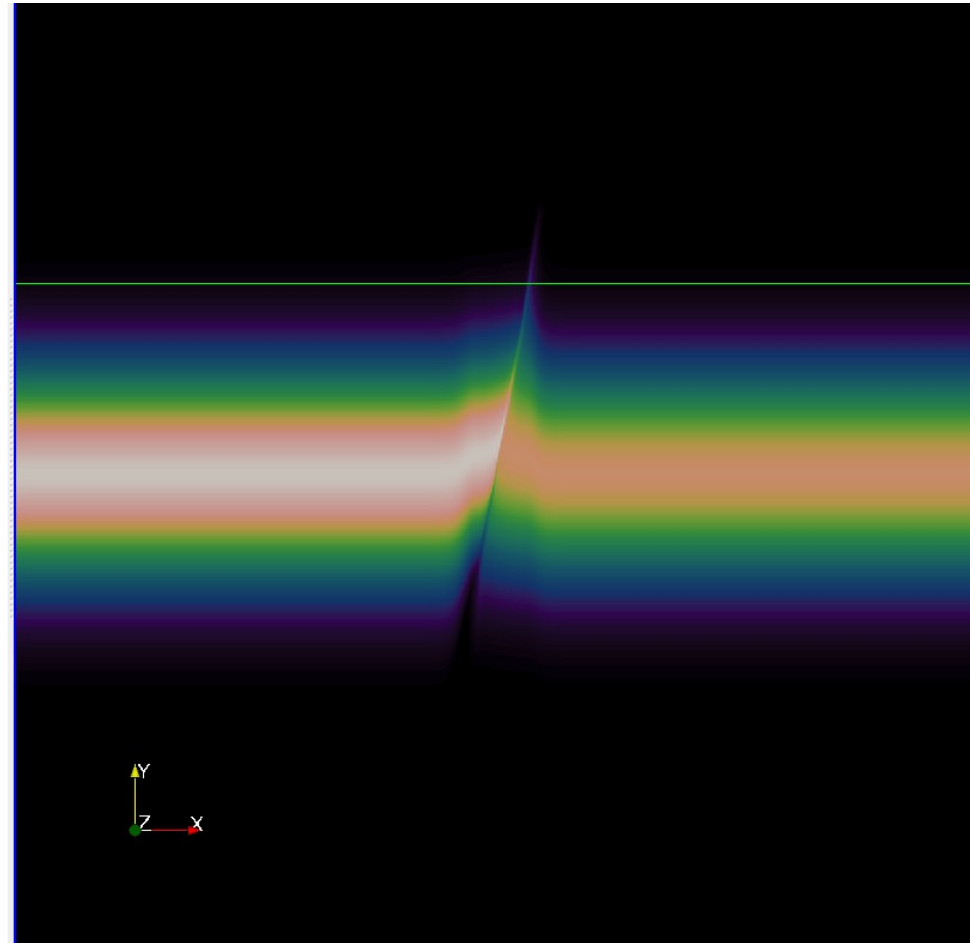
Typical Simulation Result



Heavily Damped Case
Electron Temperature: 1.5 [eV] | ($T_e/T_i = 7.5$)
Density Difference: 30%



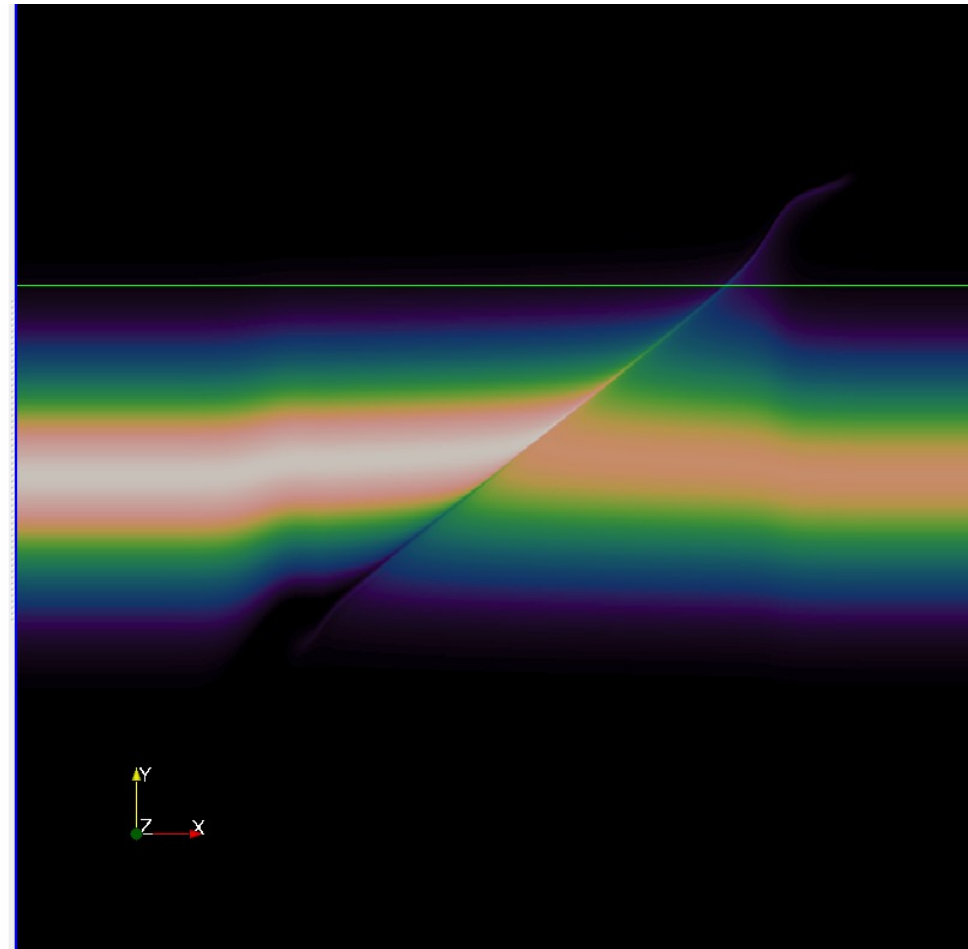
Typical Simulation Result



Heavily Damped Case
Electron Temperature: 1.5 [eV] | ($T_e/T_i = 7.5$)
Density Difference: 30%



Typical Simulation Result



Heavily Damped Case
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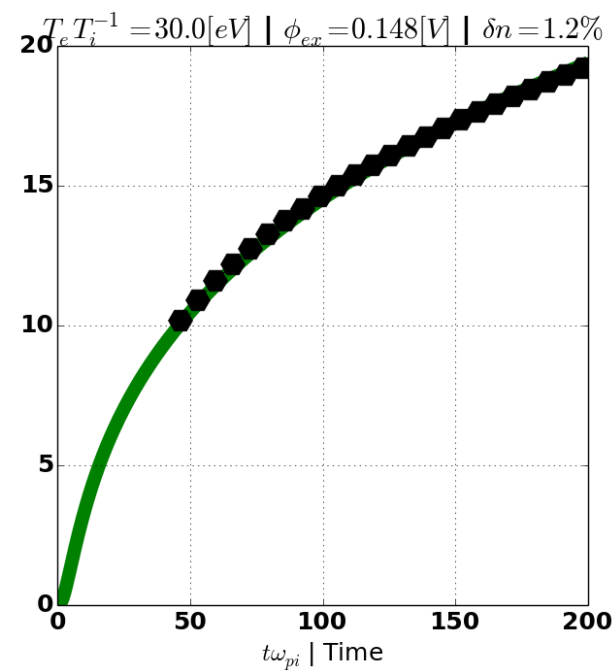
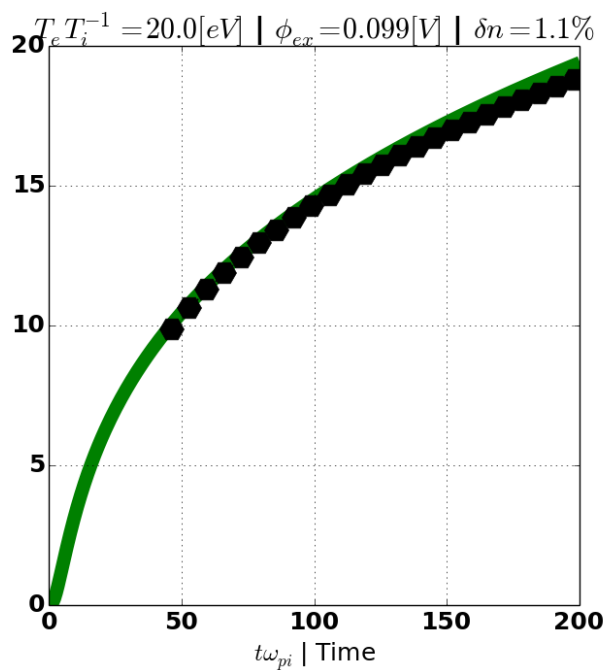
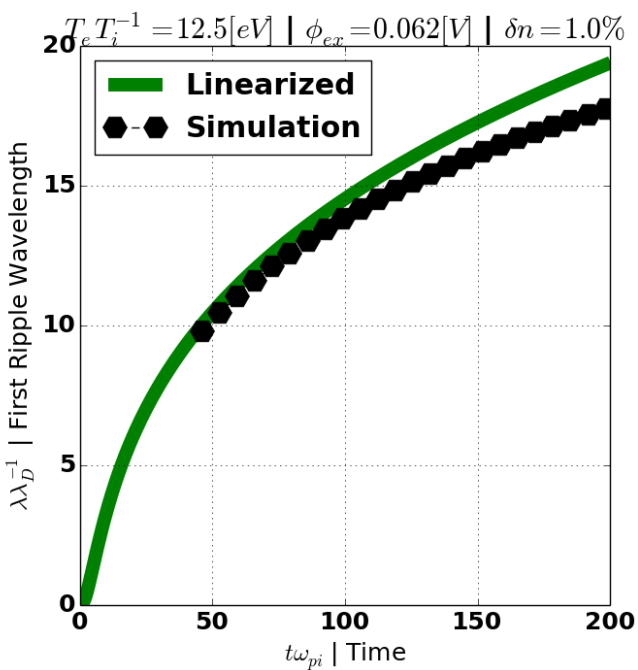
Model Verification



Comparison with Linearized Solution

– Evolution of the First Ripple Wavelength:

- Simulated weak shocks (1% jump) for different temperature ratios.
- Greater ion reflection at lower electron temperature alters the first ripple.
- Agreement improves with hot electrons, as ion reflection decreases.



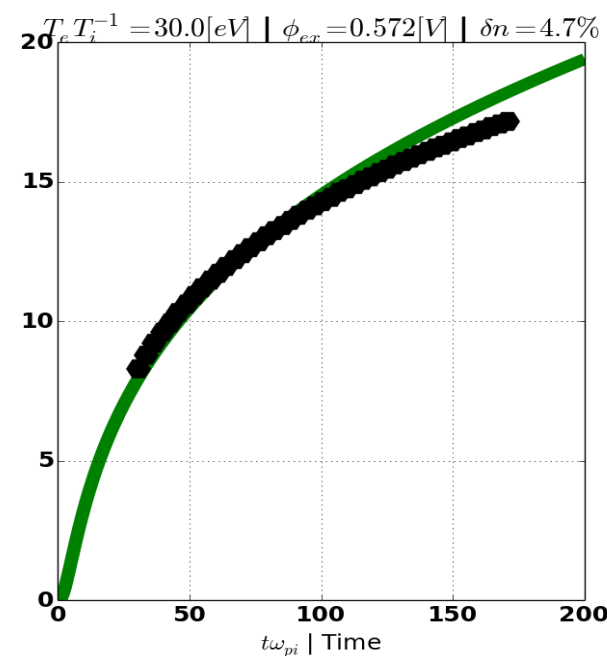
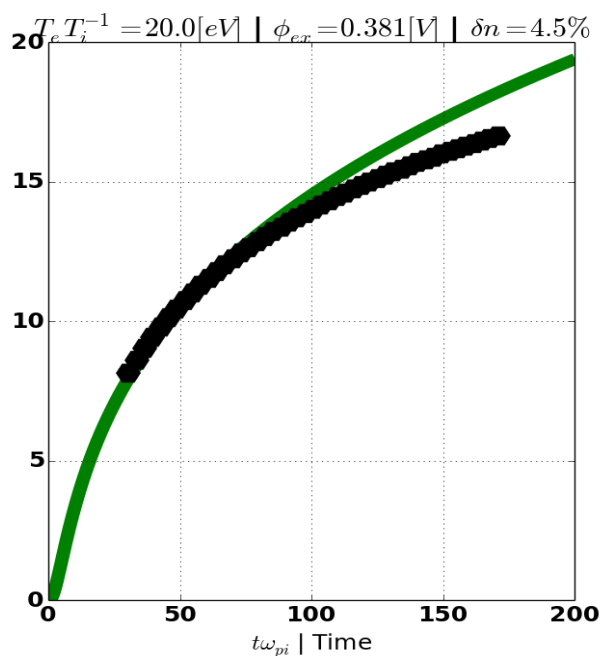
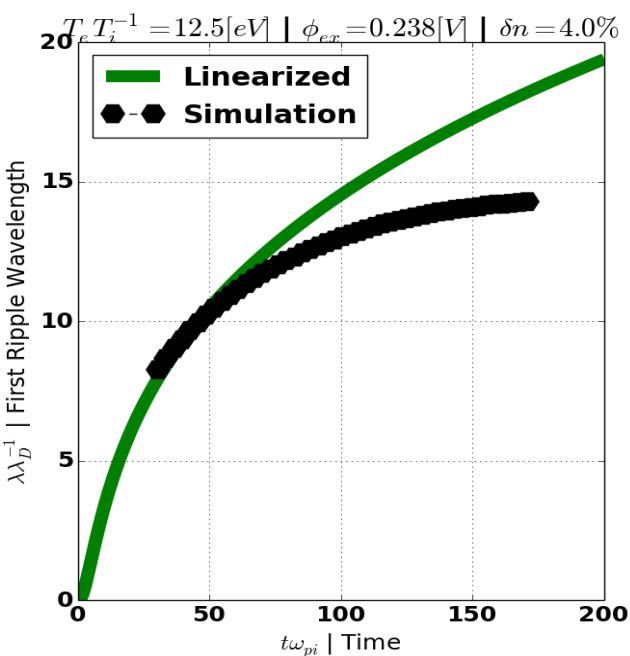


Model Verification

Comparison with Linearized Solution

– Evolution of the First Ripple Wavelength:

- Stronger shocks (4%) show poorer agreement at lower electron temperature.
- Stronger shocks reflect more ions, causing stronger dissipation.
- Agreement with linearized model improves with electron temperature.





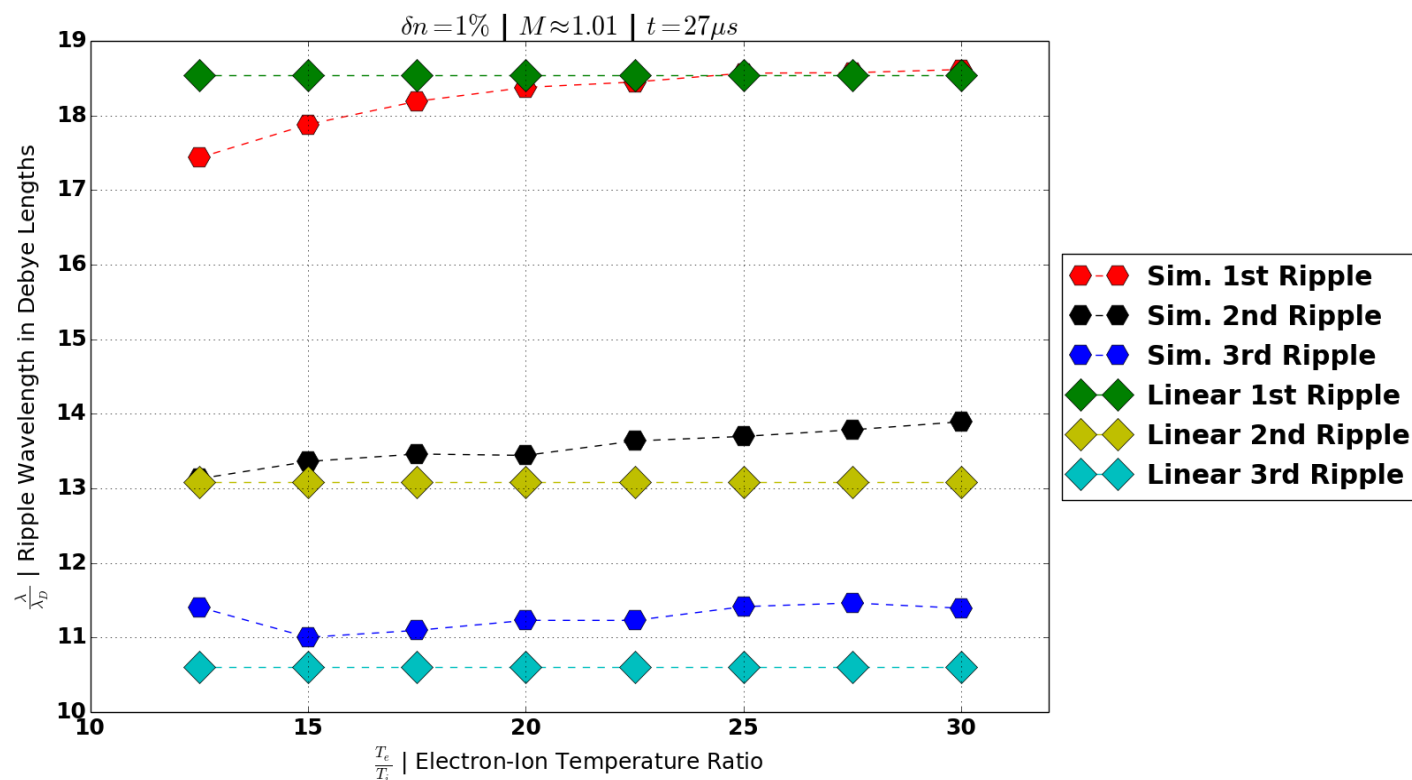
Model Verification



Comparison with Linearized Solution

– Trailing Ripple Wavelengths:

- Subsequent wave train ripples diverge from the model.
- Simulated ripples do not approach zero wavelength like the linearized model.





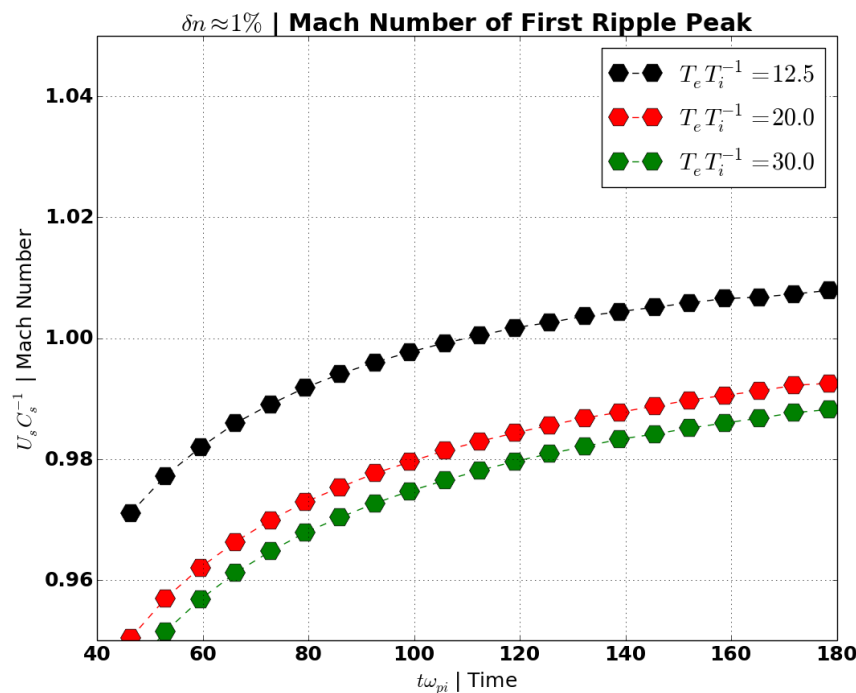
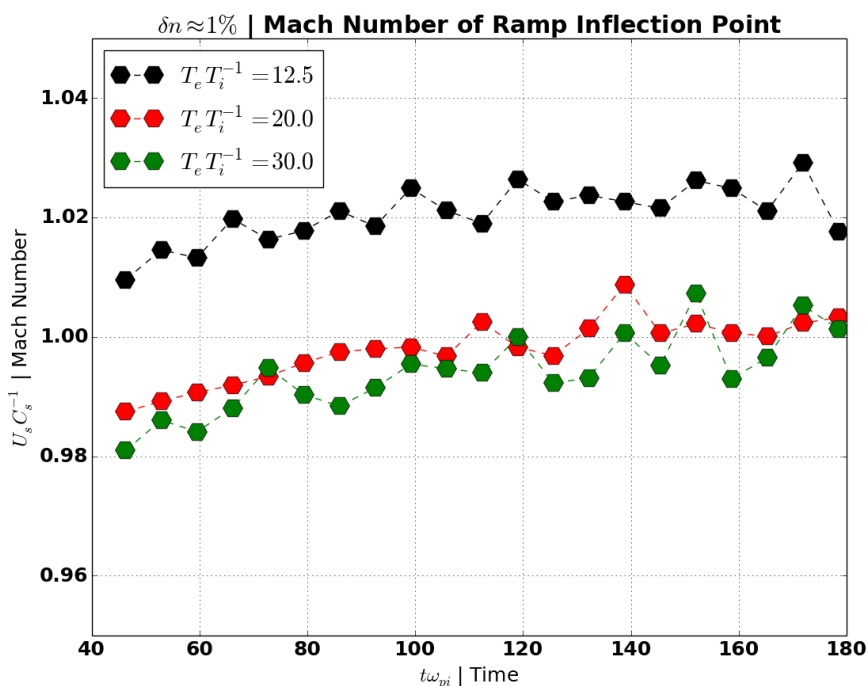
Results on Shock Structure



Other Weak Shock Results

– Shock Mach Number:

- For the same density jump (1% here),
 - Shock speed increases with electron temperature, Mach number decreases.
- The first wave train oscillation peak travels less quickly than the shock ramp.





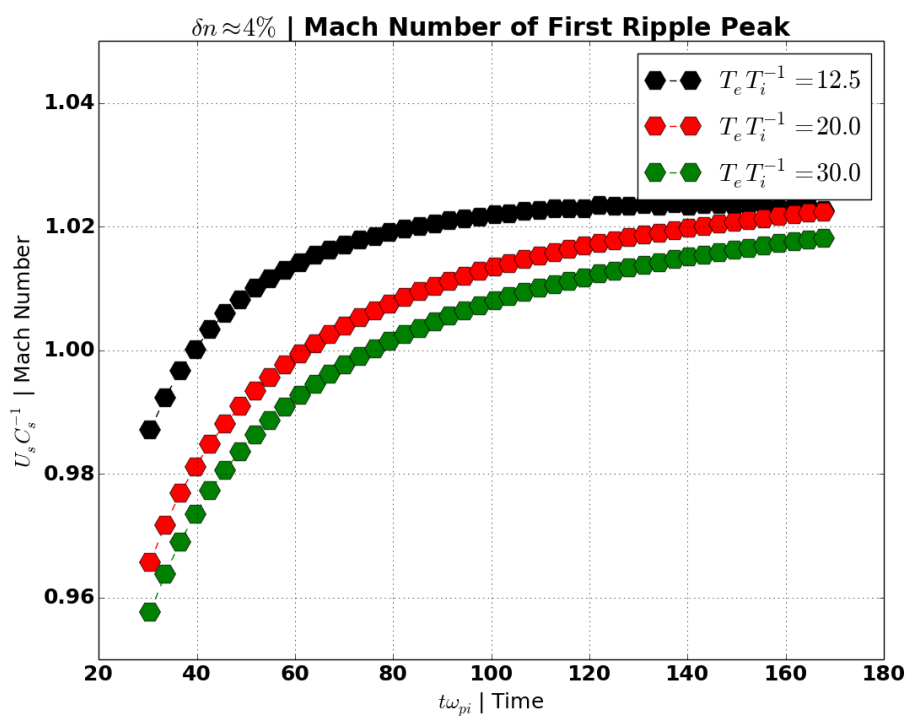
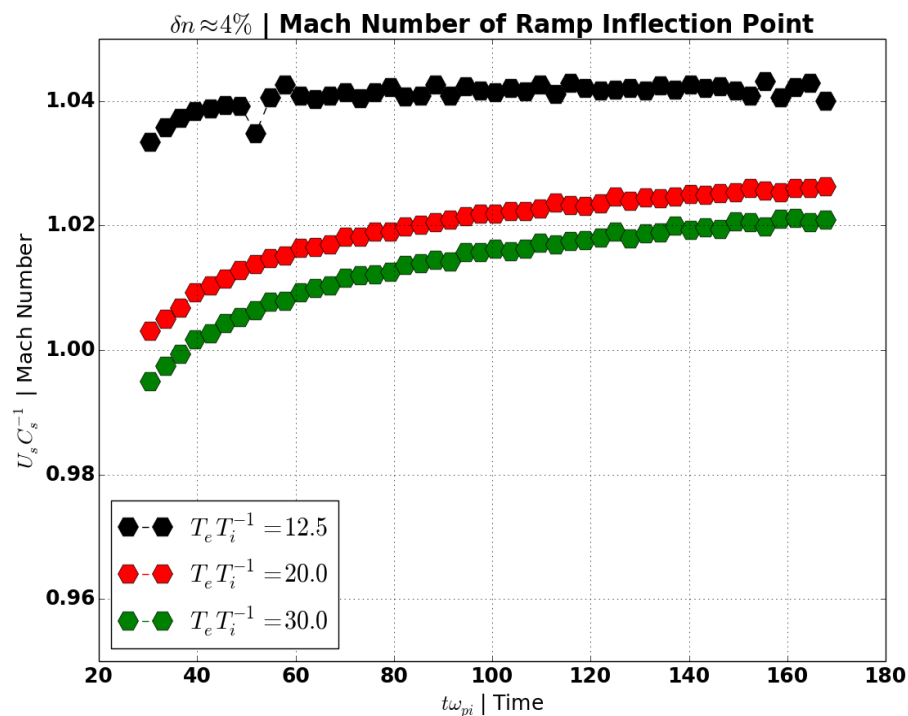
Results on Shock Structure



Other Weak Shock Results

– Shock Mach Number:

- The same trends are apparent for slightly stronger shocks (4% jump here).
- Ion reflection appears to damp the shock acceleration.





Model Validation

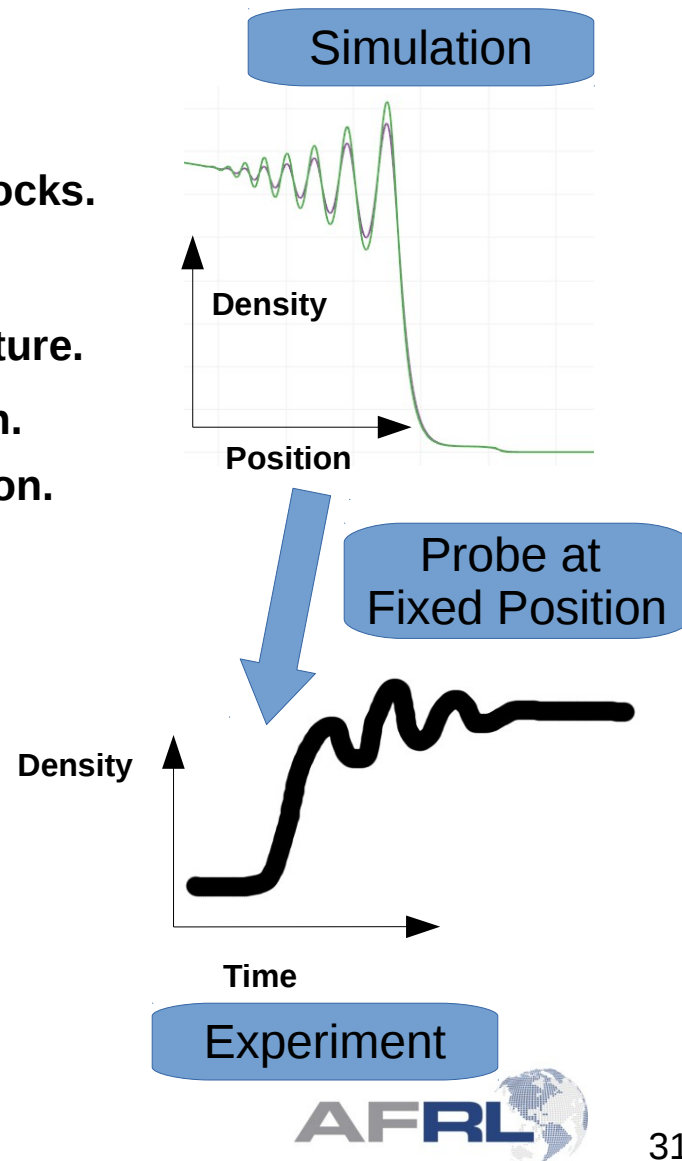


Gathering Experiment Data

- Double Plasma Device:
 - Can produce low Mach number collisionless shocks.
- Diagnostics:
 - Langmuir probes; density and electron temperature.
 - Shock speed, and density at fixed position.
 - Ion temperature is necessary for proper validation.

Validation Comparisons

- The Wave Train:
 - Simulation suggests ripples should occur for:
 - Moderate Mach numbers ($\sim 1.2 - \sim 1.6$)
 - High electron-ion temperature ratio (>10)
- Wave Train Wavelength
- Shock-Front Mach Number
- Reflected Ion Beam Velocity





Towards Validation and Extension



Towards Validation of Collisionless Model

- Verification:
 - Simulated weak shocks agree with the linearized cold-ion solution.
- Validation:
 - Results should be compared to experimental shock data.
 - Inconsistencies in published 1969 double-plasma device data hampered validation.

Future Work: Extension to Moderately Collisional Problem

- Collision Operators:
 - Presence of a few mean collisions in shock transition invalidates Vlasov equation.
 - The collisional ion-acoustic shock requires the full Boltzmann equation with appropriate choice of collision operator.
 - Moderately collisional shocks should be hybrid dispersive-dissipative shocks.
- Validation of Collision Algorithms:
 - Tuning parameters in a shock experiment can yield moderately collisional data.



Back Up Slides

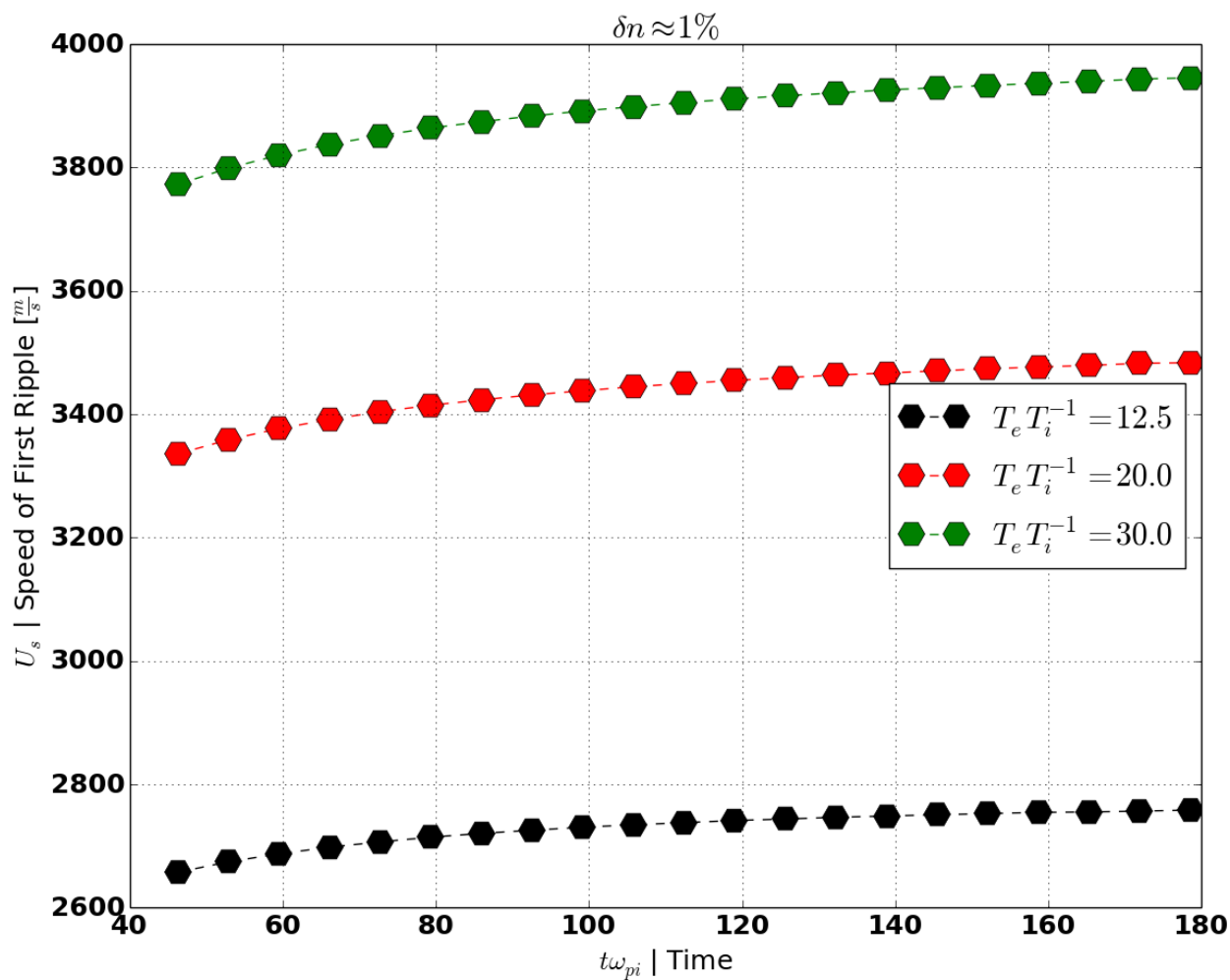




Results on Shock Structure



Example of Shock Speed at 1%





Details on Shock Structure



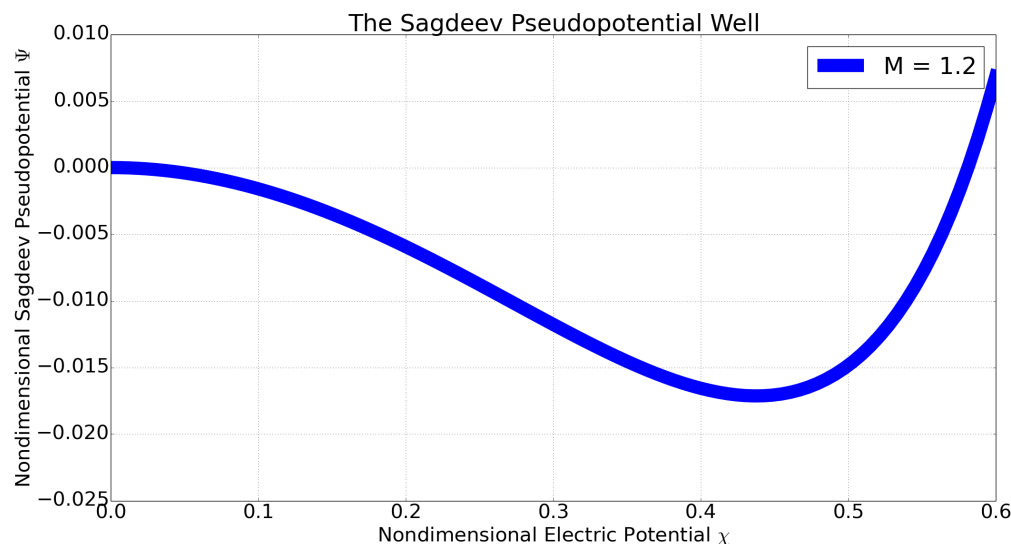
Wave Train Properties

– Sagdeev Pseudopotential:

- An analogy to motion in a potential well, describes oscillations in wave train.
- Dissipation within the well leads potential to settle at the minimum.

$$\frac{d^2\chi}{d\xi^2} = -\frac{dV(\chi)}{d\chi}$$

$$V(\chi) = 1 - e^\chi + M^2 \left(1 - \left(1 - \frac{2\chi}{M^2} \right)^{\frac{1}{2}} \right)$$





Electric Field Details

